Parallel Structure Factor

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A. INTRODUCTION

Parallel Structure Factors (PSF) program is used to compare two 3D density maps and get some factors between these two data sets, so we can know the similarity of these two maps. PSF use as input: two 3D density maps generated by P3DR, output: some factors such as Standard Rfactor, Rfactor for Phase, Phase Difference, and Correlation Coefficient. The input 3D maps have been stored in the Purdue *.PIF format.

PSF is used in conjunction with our parallel 3D reconstruction algorithm (P3DR) in Cartesian coordinates for objects without symmetry.

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B. PROGRAM INPUT

Input parameters of PSF are as follows :

map1filename	(C)
map2filename	(C)
res_hi, res_low, res_step, pixel_size	(F, F, I, F)

1. map1filename (C)

Specify the name of the PIF format 3D density map to be used for compared.

2. map2filename (C)

Specify the name of the PIF format 3D density map to be used for compared.

3. res_hi, res_low, res_step, pixel_size (F, F, I, F)

pixel_size is the pixel size for these two maps, if they are not the same as the pixel size in the map file, it will give a warning, and using the input pixel size.

res_hi and **res_low** specify the resolution range to which we compare these two maps, and the regions beyond this range will not be compared. **res_hi** is the upper radius resolution of this range, and it can't be set to a value any SMALLER than twice the size of the IMAGE pixels (the so-called Nyquist limit imposed because the Fourier transform of digitized data only extends to a spatial frequency of 1.0/(2*pixel size). **res_low** is the lower radius resolution of this range, and it must be equal or larger than **res_hi**. Normally **res_low** can be set to maximum value which means from the canter where radius nearly 0.

res_step is the resolution step size, in another word, it means how many segment should be made in the range from **res_hi** to **res_low**.

C. EXAMPLE PSF INPUT CONTROL PARAMETERS FILE

hv.map.even hv.map.odd 6.0, 50.0, 50, 2.23

D. PROGRAM EXECUTION

Normal operation of PSF will print out these factors. It is used for comparing two maps (usually the maps generate by odd or even particles). Then we can try to find the effective resolution of our map using the orientation files.

For example:

Execute PSF with 8 nodes using MPI, the command will be:

% mpirun -nolocal -machinefile mach -np 8 PSF < Psf.in > Output

or

% mpirun -np 8 PSF < Psf.in > Result

Psf.in is the script of the input control parameters file, and the **Output** file will be the table of all factors with about **res_step** rows. We use I/O redirect methods. The **mach** file is used for specifying the hosts of the cluster that you want to use. Please modify it to indicate the host names of your cluster. If use second command, it will use the default machine configuration under MPICH directory.

For details of running MPI and specifying hosts in the host file, see user guide of MPICH at http://www-unix.mcs.anl.gov/mpi/mpich/.

E. PROGRAM NOTES

The directories of PSF source code are:

Commpl	ĸ	common	routine	directory

- |-- PSFsrc !PSF source codes directory
- I-- Vfftpk IFFT library codes directory
- -- include !include files directory
- |-- Makefile

1. In Fourier Domain: annulus = FFT_DIM * pixel_size / resolution anuulus <= FFT_DIM / 2

so: resolution >= 2 * pixel_size

2. FFT transforms used (N is even):

Analysis: $F(h, k) = \frac{1}{N} \sum_{x=0}^{N-1} \sum_{y=0}^{N-1} f(x, y) \exp(-2\pi i (xh+yk)/N)$ Periodicity: F(h, k) = F(h+N, k) = F(h, k+N) = F(h+N, k+N)Conjugate: $F^*(-h, -k) = F(h, k)$

3. factors formula:

 $A1 = sqrt(real(F1)^{**}2 + amig(F1)^{**}2)$

A2 = sqrt(real(F2)**2 + amig(F2)**2)

- a. Standard Rfactor
 - R-SFactor = $\Sigma |A1-A2| / \Sigma A1$
- b. Rfactor for Phase

 $R-phase = \Sigma(sqrt((real(F1)-real(F2))**2 + (aimag(F1)-aimag(F2))**2)) / \Sigma A1$

c. Phase Difference

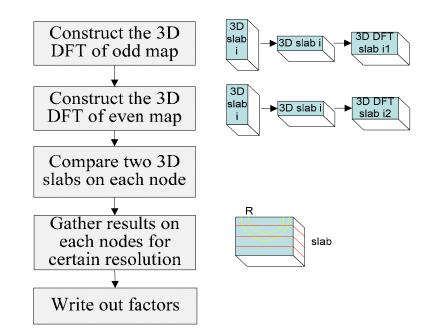
phase-diff = Σ |atan(aimag(F1) / |real(F1)|) - atan(aimag(F2) / |real(F2)|) | / n

d. Correlation Coefficient

 $CC = \Sigma((A1 - \overline{A1})(A2 - \overline{A2})) / \operatorname{sqrt}(\Sigma((A1 - \overline{A1})^{**2}) * \Sigma((A2 - \overline{A2})^{**2}))$

F. REFERENCES

G. FLOW CHART FOR PSF PROGRAM



PSF

- |--- call usage
- |--- call mpi_init
- |--- call check_map
- |--- call check_map
- |--- call bcast_parameters
- |--- call intlz_params
- |--- call intlz_arrays

- !! main program
 !! print out usage
 !! mpi initialization
 !! check the 1st map
 !! check the 2nd map
 !! broadcast parameters
 !! initialize parameters
- !! initialize arrays

|--- call vrffti
|--- for each map do
 |--- call read_map
 |--- call fft_2dfft
 |--- call arrange_3d_1
 |--- call exch_3d_1
 |--- call cfft_1d
|--- call comp_sfactor
|--- call mpi_finalize

CHECK_MAP |--- call pif_open |--- call pif_read_gh |--- call pif_read_dh |--- call pif_close

INTLZ_PARAMS |--- call trans_length_essl

INTLZ_ARRAYS |--- call set_indices |--- call set_indices |--- call set_indices |--- call set_indices

READ_MAP

!! initialize fft parameter

!! read 3D map and scatter slab to each node
!! apply 2D DFT onto the 2-slab of 3D model
!! rearrange the slab for exchange
!! exchange slabs among nodes for 1D DFT
!! 1D DFT along z axis with complex number
!! compute the factors of the two maps
!! finalize mpi

!! check the map
!! open the pif file for read
!! read the global header of the pif file
!! read the data header of the pif file
!! close image file

!! initialize internal parameters
!! calculate suitable FFT_DIM

!! initialize internal arrays
!! calculate frst_lst_hk
!! calculate frst_lst_y
!! calculate frst_lst_u
!! calculate frst_lst_z

!! read and scatter slab of 3D model map!! open the pif file for read!! read the global header of the pif file!! read the data header of the pif file

!! read 1 slab of pif file in 4-byte
!! read 1 slab of pif file in 2-byte
!! close image file